

# Programme 8, projet 8

Observatoires fond de mer pluridisciplinaires

NEPTUNE CANADA : PIEZOMETER test procedure						
établi le :	par :	Réf :	n° analytique :	Indice :		
03/05/2011	J. Legrand	RDT/EIM/11-12	A080806	В		

#### Diffusion :

IFREMER	NEPTUNE CANADA
Auffret Yves (RDT/EIM)	Pautet Lucie (Neptune Canada)
	Wallace Kim (Devocean)
	Williams Jason (Highland-Tech)



### DOCUMENT VERSIONS

Version	Date	Description	Reference secretariat
A	03/05/2011	Document creation	RDT/EIM/11-12
В	05/05/2011	§3 modification	RDT/EIM/11-12

#### SUMMARY

1 - Sensors connection	3
2 - Connection to your Network	4
3 – Piezometer configuration with terminal	4
3.1 – Clock synchronisation	4
3.2 - Detect sensors connected to MDS	5
3.3 - Edit experiment	5
3.4- Edit deployment	5
3.5- Edit sample period	5
3.6- Edit start date	5
3.7- Edit stop date	5
3.8- Edit Settings	5
3.9 - Start Record	6
3.10 – Data retrieve	6
4 – Piezometer configuration with WINPiezo software	7



The piezometer is shipped in different parts :

- ➢ The electronic housing,
- The cable 2 from the housing to the C/DC,
- The cable from the C/DC to your cable (1),
- $\succ$  The sensors,
- > The cable from the housing to the first sensor,
- > The other cables between each sensors.



#### **1** - Sensors connection

You have to connect the first sensor (the only sensor with a 6 pins microfit connector) to the electronic housing, using the cable 3 (Subconn micro male 8 pins to microfit 6 pins). (blue cable on the picture below).







Then you can connect the other side of the first sensor to the second one with a yellow cable (Microfit 4 pins to microfit 4 pins).

Repeat the same operation for the other sensors. The last sensor is not connected on one side.

## 2 - Connection to your Network

Connect the electronic housing to the C/DC using the cable 2 (Subconn micro male 10 pins to C/DC),

Connect the 1m extension cable (P1 to P2, special Subconn micro female 8 pins to Subconn 8 pins male) to your 100m cable (1).

You are now ready to connect the Piezometer on NEPTUNE network via a RS485/Ethernet converter and test it with the driver developed by Tim.

## **3** – Piezometer configuration with terminal

After powered up, the piezometer has to be configured to run in automatic mode and allow data retrieve from your driver.

A series of command has to be sent to the piezometer. This can be done with a terminal or with the piezometer HMI "WinPIEZO2.0" (See chapter 4)

For a better comprehension, 2 different colours are used to detail the frames sent to the piezometer (blue) and the frame received from the piezometer (green).

<u>3.1 –Clock synchronisation</u> Send the command <<u>NULL></u>man\_sync= aa/mm/jj hh:mm:ss<<u>CR></u><u>LF></u> The piezometer answers : #manual synchronization of the date : aa/mm/jj hh:mm:ss<<u>CR></u><u>LF></u>



3.2 - Detect sensors connected to MDS Send the command <NULL><NULL>detect<CR><LF> The piezometer answers : #bus 1 detection ... #bus 1 listing : #bus 1 detection in progress... #bus 1 listing B1;N01;MPT Keller;SN 00002 B1;N02;MPT Keller;SN 00015 B1;N03;MPT Keller;SN 00035 B1;N04;MPT Keller;SN 00037 B1;N05;MPT Keller;SN 00038 #end of bus 1 listing<CR><LF>

<u>3.3 - Edit experiment</u> Send the command <<u>NULL></u>experiment=<u>NEPTUNE</u><<u>CR></u><u>LF></u> The piezometer answers : #experiment: NEPTUNE<<u>CR></u><u>LF></u>

<u>3.4- Edit deployment</u> Send the command <<u>NULL>deployment=0DP1027<CR><LF></u> deployment=ODP1027<CR>" The piezometer answers : #deployment: ODP1027<CR><LF>

<u>3.5- Edit sample period</u> Send the command <<u>NULL></u>sample=5<<u>CR></u><u>LF></u> The piezometer answers : #sampling interval: 5s<<u>CR></u><u>LF></u>

<u>3.6- Edit start date</u> Send the command <<u>NULL></u>dt\_start=aa/mm/jj hh:mm:ss<<u>CR></u>LF> The piezometer answers : #the start date is set to: aa/mm/jj hh:mm:ss<<u>CR></u>LF>

<u>3.7- Edit stop date</u> Send the command <<u>NULL></u>dt\_stop=aa/mm/jj hh:mm:ss<<u>CR></u>LF> The piezometer answers : #the stop date is set to: aa/mm/jj hh:mm:ss<<u>CR></u>LF>

<u>3.8- Edit Settings</u> You can check the different parameters set with the command <<u>NULL><NULL>settings<CR><LF></u> The piezometer answers :



#experiment : NEPTUNE
# deployment : ODP1027
#maximum size for data file: 1024 Ko
#sampling interval for supply voltage : 30mn
#sampling interval for tilt angle : 30mn
#sampling interval : 5s
#dt\_start : 07/01/01 00:00:00
#dt\_stop : 07/01/15 23:59:59<CR><LF>

<u>3.9 - Start Record</u> The piezometer is now ready to start record Send the command <<u>NULL></u>-<u>NULL></u>rec<<u>CR></u>-<u>LF></u> The piezometer answers : #recording starting<<u>CR></u>-<u>LF></u>

<u>3.10 – Data retrieve</u>

Once the piezometer is configured, the protocol to retrieve data is the following (commands implemented in the NEPTUNE driver written by Tim).

The following command allows to retrieve all data stored in the piezometer memory. This command should be used only the first time when the driver starts :

<NULL>data=1;n<CR><LF>

After a few seconds, the piezometer answers : #all data<CR><LF> YYMMDDHHMMSS<CR><LF> B1;N01;P1;D1;Q1;C1<CR><LF> B1;N02;P2;D2;Q2;C2<CR><LF> B1;N03;P3;D3;Q3;C3<CR><LF> B1;N04;P4;D4;Q4;C4<CR><LF> B1;N05;P5;D5;Q5;C5<CR><LF> B1;N06;P6;D6;Q6;C6<CR><LF> retrieve all the measurements

n times (1 per measurement)

#end of data, CHK: xxxxxxxxx<<CR><LF>

Where

YYMMDDHHMMSS is the Date & Time , B1 is the bus number (Always B1 for NEPTUNE CANADA deployment), N01 to N06 are the sensor number (see table), P is the physical temperature value from the sensor (in °C), D is the raw temperature value from the sensor, Q is the physical pressure value from the sensor (in kPa), C is the raw pressure value from the sensor.

NB:

P and Q have the following format : +/-XXX.YYY D and C have the following format : +/-XXXXX

After that, periodically (period to be defined), the following command allows to retrieve only the last measurements which have not been retrieved yet :



<NULL><NULL>data=1;y<CR><LF>

retrieve last measurements

The response format is the same that for the "data=1;n" command.

Example :

<NUL><NUL>data=1;y<CR>

Last Data recovery command

Response from the piezometer

#all data<CR><LF> 100225095818 <CR><LF> B1;N01;+015.977;27112;+000.743;30191<CR><LF> B1;N02;+016.426;26531;+002.904;31729<CR><LF> B1;N03;+016.085;27078;+002.199;31243<CR><LF> B1;N04;+016.226;26856;+001.015;32170<CR><LF> B1;N05;+016.388;26701;+000.676;32988<CR><LF> B1;N06;+016.278;26799;+000.404;33017<CR><LF> 100225095848 <CR><LF> B1;N01;+015.987;27100;+000.743;30191<CR><LF> B1;N02;+016.430;26525;+002.904;31729<CR><LF> B1;N03;+016.088;27074;+002.199;31243<CR><LF> B1;N04;+016.230;26851;+001.015;32170<CR><LF> B1;N05;+016.389;26700;+000.676;32988<CR><LF> B1;N06;+016.283;26794;+000.404;33017<CR><LF> 100225095918 <CR><LF> B1;N01;+015.994;27091;+000.743;30191<CR><LF> B1;N02;+016.434;26521;+002.894;31728<CR><LF> B1;N03;+016.092;27069;+002.207;31244<CR><LF> B1;N04;+016.234;26847;+001.015;32170<CR><LF> B1;N05;+016.394;26693;+000.676;32988<CR><LF> B1;N06;+016.285;26791;+000.404;33017<CR><LF> #end of data, CHK: 0000036557<CR><LF> \$

#### Wake-up problem :

If the piezometer does not answer to a command or send the following error frame : \*Error: wrong char<CR><LF>

Please wait 1 second and send again the command, this can be the result of a wake-up problem.

## 4 – Piezometer configuration with WINPiezo software

The different commands described in chapter 3 can be sent with the WINPiezo2.0 software.

- Launch the software by clicking the WINPiezo2.0.exe 🧕,
- Click on Settings and choose the port number and the baud rate (115200) 🔊
- Connect to the MDS <sup>10</sup>,
- Synchronise the clock
- Detect the sensors **?**



- Configure the parameters 🕅, Start the recording 💽 \_
- \_

If you want to stop the recording, use

WinPIEZO		- • ×
About. 1 - Settings 7 - Qui	t	
	2 - Connect	
MDS Programmation MPT Calibration MDS Files	2 - Connect  Last hour measures  3 - Clock synchronisation  4 - Detect sensors  5 - Configure the parameters  6 - Start Record	ő
MDS mode : unknown		